# Using CVFED hydraulic models to inform the C2VSim groundwatersurface water model

Holly Canada, PE David Ford Consulting Engineers, Inc.

> CWEMF annual meeting April 12, 2016



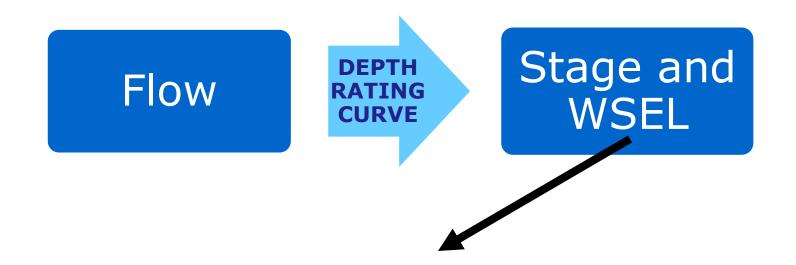
## Collaborators

- Tariq Kadir (DWR).
- Can Dogrul (DWR).
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- Tom Molls (David Ford Consulting Engineers).
- Ric McCallan (David Ford Consulting Engineers).
- William Sicke (David Ford Consulting Engineers).
- Ali Taghavi (RMC).
- Mesut Cayar (RMC).





• To verify and refine the C2VSim channel depth rating curves.



#### Groundwater – surface water interaction



#### Outline

- C2VSim model
- CVFED HEC-RAS models.
- Verify C2VSim coarse grid parameters.
- Refine C2VSim parameters (fine grid model development)
- Summary.



## C2VSim groundwater-surface water model

- Integrated hydrologic model.
- Developed by DWR for Central Valley water management planning.
- Simulates water movement through the interconnected land surface, surface water, and groundwater flow systems.



### **C2VSim model versions**

- Two representations of surface water movement:
  - 1. Water balance (instantaneous routing).
  - 2. Kinematic wave routing.
- Two grid size options:
  - 1. Coarse (1,393 elements).
  - 2. Fine (+32,500 elements).



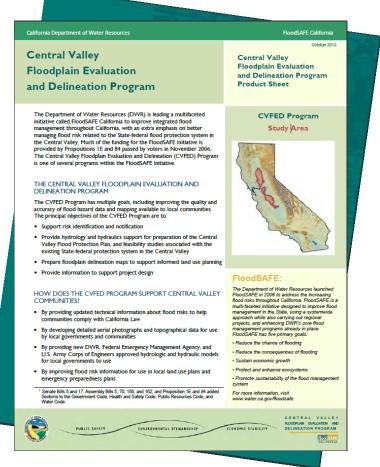
## What C2VSim models did we use?

- For the coarse grid kinematic wave model, we verified:
  - Depth-flow rating curves.
  - Velocity-flow rating curves.
  - Cross section geometries.
  - Channel slope values.
  - Manning's n values.
- To aid development of the **fine grid** kinematic wave model, we **refined**:
  - Depth-flow rating curves.
  - Channel invert elevation.



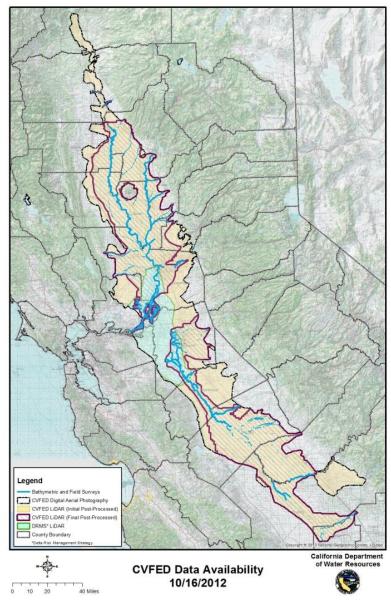
## The Central Valley floodplain evaluation and delineation program (CVFED)

- Paterno Decision 2003, DWR White Paper & Hurricane Katrina 2005, Prop 84 & 1E 2006, SB/AB Bills 2007.
- CVFED in 2008.
- \$110M Program (Prop. 84 & 1E).
- Three Projects:
  - Project 1 Topography Acquisition.
  - Project 2 Riverine and Overland Hydraulic Model Development.
  - Project 3 Floodplain Mapping.





## **CVFED topography development**

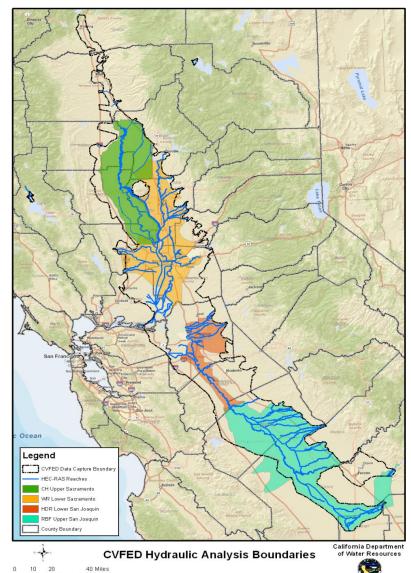


• Lidar

- Initial post-processing
  - 7,800 sq. mi.
- Final post-processing
  - 5,800 sq. mi.
- DRMS LIDAR
  - 1,200 sq. mi.
- Digital Aerial Photography
  - 9,000 sq. mi.
- Field Surveys
  - 3,000 cross-sections
- Bathymetric Surveys
  - 2,500 cross-sections



## **CVFED riverine/hydraulic models**



 1-D riverine models (HEC-RAS)

- 1,650 miles of streams
- 2-D overland flow models (FLO-2D)
  - 5,950 square miles
- 1-D/2-D riverine/overland models (TUFLOW)
  - Yuba River and Cache Creek



## **CVFED hydraulic models**

- HEC-RAS hydraulic modeling program.
- Full dynamic wave routing.
- 1-dimensional.
- Unsteady-state.
- Channels, levees, and embankments are based on topography data and existing conditions.
- Sacramento and San Joaquin river systems.



## VERIFY C2VSim COARSE GRID MODEL PARAMETERS



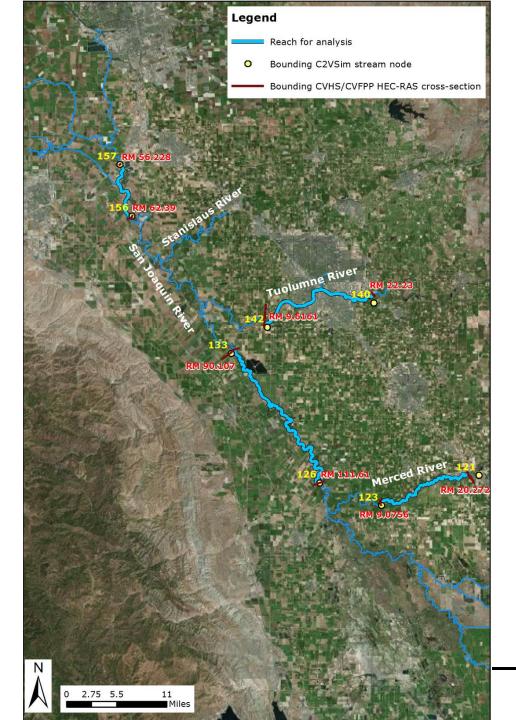
### **Verified model parameters at 8 representative reaches**

- 1. Upper Sacramento River.
- 2. Feather River.
- 3. American River.
- 4. Lower Sacramento River.
- 5. Lower SJR.
- 6. Tuolumne River.
- 7. Upper SJR.
- 8. Merced River.



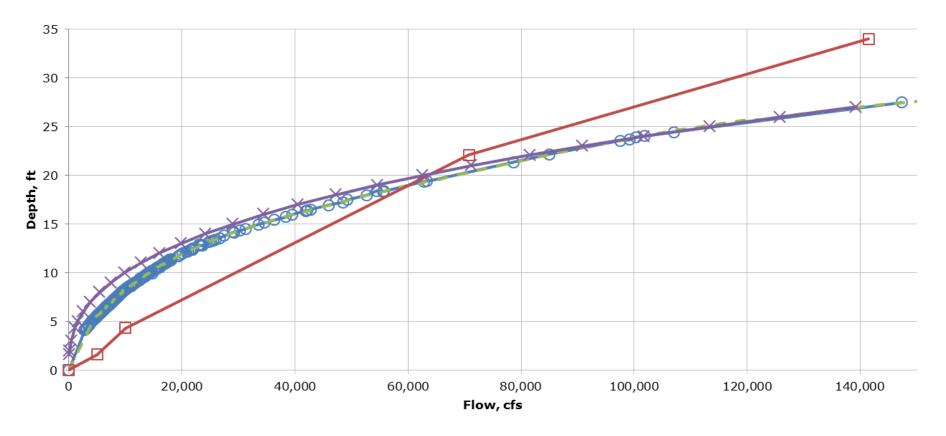








#### **Compared depth-flow rating curves** (example location where similar)



----- CVHS/CVFPP HEC-RAS cross section at Sacramento Redding 240.00 (1997)

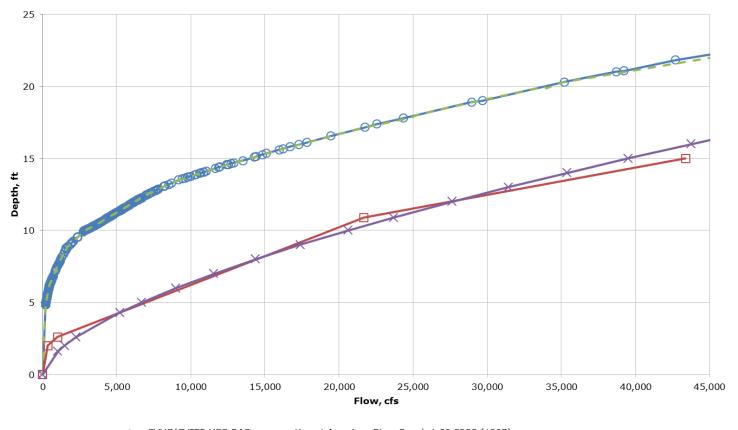
CVHS/CVFPP HEC-RAS cross section at Sacramento Redding 240.00 (1986)

C2VSim river node 231, original model

C2VSim river node 231, kinematic wave model



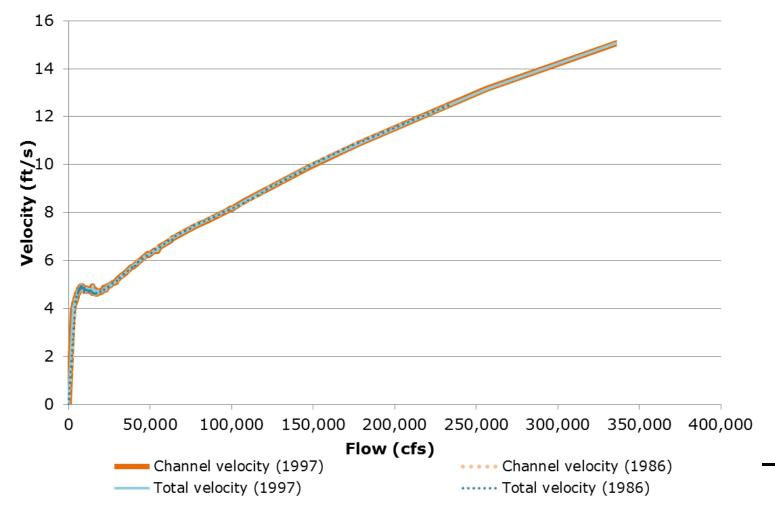
### **Compared depth-flow rating curves** (example location where different)



- ----- CVHS/CVFPP HEC-RAS cross section at American River Reach 1 20.3333 (1997)
- - CVHS/CVFPP HEC-RAS cross section at American River Reach 1 20.3333 (1986)
  - C2VSim river node 376, original model
  - C2VSim river node 376, kinematic wave model

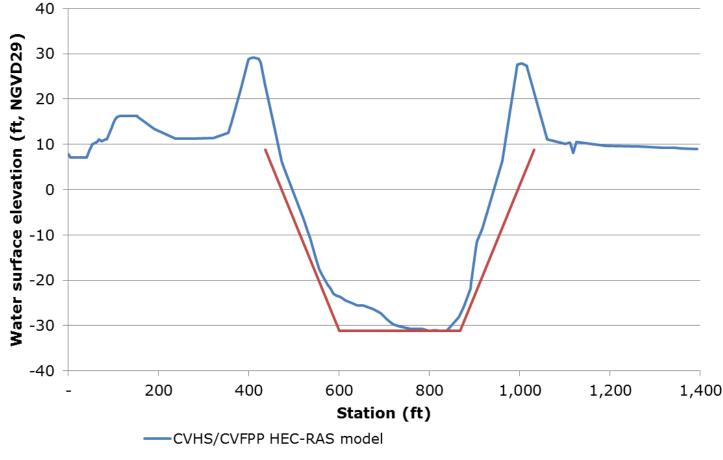


#### **Developed velocity-flow rating curves from HEC-RAS for future comparison**





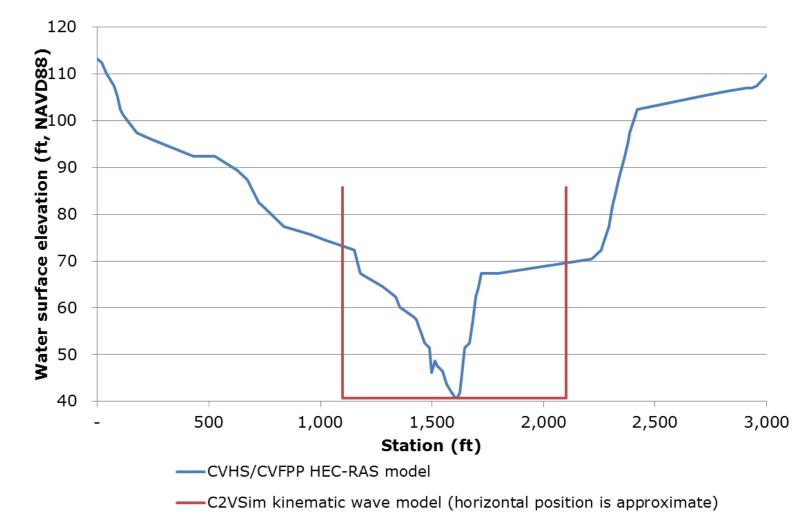
## **Compared cross section geometries** (example location where similar)



C2VSim kinematic wave model (horizontal position is approximate)



## **Compared cross section geometries** (example location where different)





#### **Other model parameters**

- Channel slope.
- Manning's n.



## REFINE C2VSim PARAMETERS (FINE GRID MODEL DEVELOPMENT)



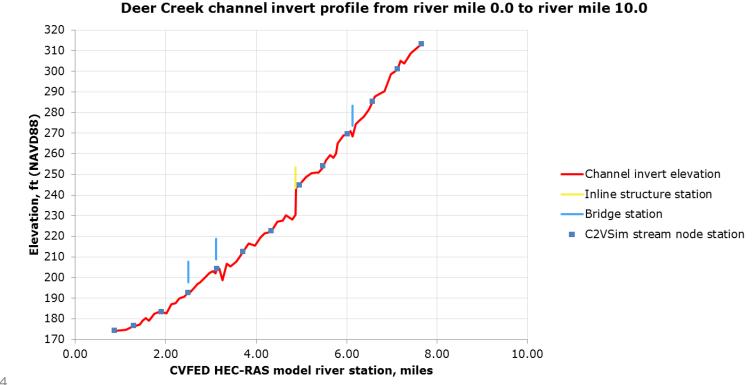


 Identified C2VSim stream nodes within CVFED model extents.

> 2,384 out of 4,569 total stream nodes (52%)



2. Estimated channel invert elevations at C2VSim stream nodes and plotted the channel invert profile along each stream reach.



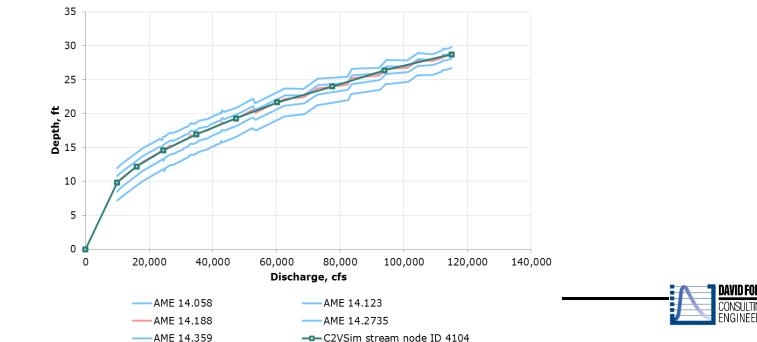


- **3.** Developed depth-flow rating curves:
  - 1. Identified 195 representative rating curve locations:
    - Beginning of each reach.
    - End of each reach.
    - Near CVHS analysis points.
  - 2. Selected the 5 nearest CVED HEC-RAS cross sections to each representative rating curve location.
  - 3. Ran the CVFED HEC-RAS models.
    - Available historical flow events w/ lowest baseflow to populate rating curves.



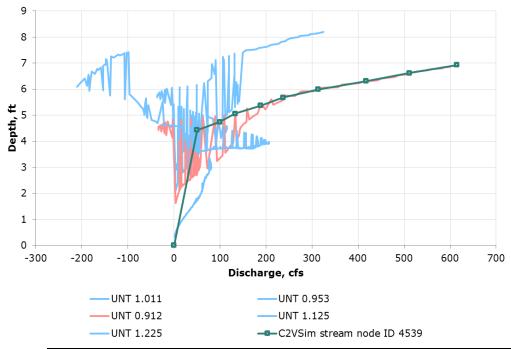
**3.** Developed depth-flow rating curves (continued):

- 4. Plotted the set of 5 rating curves at each representative rating curve location.
- 5. Fitted a 10-point smoothed curve.
- 6. Supplemented low-flow ends of rating curves.



### **Depth-flow rating curve locations for further analysis**

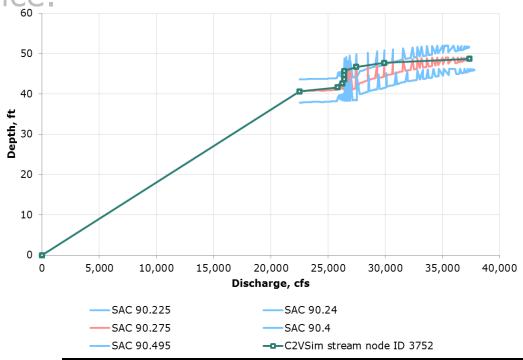
- High backflow or negative flow.
- Limited information at the low-flow end.
- Downstream constant stage boundary influence.





### **Depth-flow rating curve locations for further analysis**

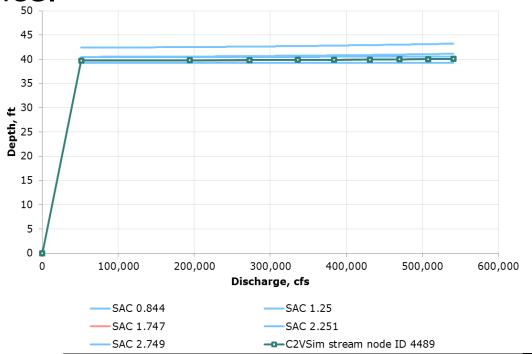
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### Summary

- CVFED hydraulic models can help inform C2VSim groundwater-surface water model by:
  - Verifying existing C2VSim parameters.
  - **Refining** C2VSim parameters.
- Further analysis necessary at complex areas or C2VSim nodes outside of CVFED model boundaries.



#### What other synergies can we find with existing California water models?

